

1. (14 points) For the matrix

$$A = \begin{pmatrix} 3 & 1 & 0 & 0 & -5 \\ 1 & 0 & -1 & 1 & 2 \\ 1 & 0 & -1 & 0 & -2 \\ 5 & 1 & -2 & 1 & -5 \end{pmatrix}$$

Compute a basis for and indicate the dimension of (a) the nullspace (the solution space of the homogeneous system), (b) the column space, and (c) the row space.

Put A in Reduced Echelon Form.

$R_1 \leftrightarrow R_3$:

$$\begin{pmatrix} 1 & 0 & -1 & 0 & -2 \\ 1 & 0 & -1 & 1 & 2 \\ 3 & 1 & 0 & 0 & -5 \\ 5 & 1 & -2 & 1 & -5 \end{pmatrix}$$

$R_2 \rightarrow R_2 - R_1$, $R_3 \rightarrow R_3 - 3R_1$, $R_4 \rightarrow R_4 - 5R_1$:

$$\begin{pmatrix} 1 & 0 & -1 & 0 & -2 \\ 0 & 0 & 0 & 1 & 4 \\ 0 & 1 & 3 & 0 & 1 \\ 0 & 1 & 3 & 1 & 5 \end{pmatrix}$$

$R_2 \leftrightarrow R_3$:

$$\begin{pmatrix} 1 & 0 & -1 & 0 & -2 \\ 0 & 1 & 3 & 0 & 1 \\ 0 & 0 & 0 & 1 & 4 \\ 0 & 1 & 3 & 1 & 5 \end{pmatrix}$$

$R_4 \rightarrow R_4 - R_2 - R_3$:

$$Q = \begin{pmatrix} 1 & 0 & -1 & 0 & -2 \\ 0 & 1 & 3 & 0 & 1 \\ 0 & 0 & 0 & 1 & 4 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

General solution of the homogeneous system is: $x_5 = r$, $x_4 = -4r$, $x_3 = s$, $x_2 = -3s - r$, $x_1 = s + 2r$. So a basis for the nullspace is

$$\mathbf{e}_r = \begin{pmatrix} 2 \\ -1 \\ 0 \\ -4 \\ 1 \end{pmatrix}, \quad \mathbf{e}_s = \begin{pmatrix} 1 \\ -3 \\ 1 \\ 0 \\ 0 \end{pmatrix}.$$

The basis for the column space consists of the first, second and fourth columns of A . The basis for the row space consists of the nonzero rows of Q .

2. (14 points) Let $L : V \rightarrow W$ be a linear map between vector spaces

(a) Define the Kernel of L and show that it is a subspace. Include a statement of which vector space it is a subspace.

(b) Assume that the zero vector θ is the only vector in the kernel. Show that L is a one-to-one mapping, that is $L(\mathbf{v}_1) = L(\mathbf{v}_2)$ only when $\mathbf{v}_1 = \mathbf{v}_2$.

(a) The Kernel of L is the subset of V equal to $\{\mathbf{v} : L(\mathbf{v}) = \theta\}$.

If $L(\mathbf{v}) = L(\mathbf{w}) = \theta$, then $L(\mathbf{v} + \mathbf{w}) = L(\mathbf{v}) + L(\mathbf{w}) = \theta$ and $L(c\mathbf{v}) = cL(\mathbf{v}) = \theta$. So the kernel is a subspace of V .

(b) If $L(\mathbf{v}_1) = L(\mathbf{v}_2)$, then $L(\mathbf{v}_1 - \mathbf{v}_2) = L(\mathbf{v}_1) - L(\mathbf{v}_2) = \theta$ and so $\mathbf{v}_1 - \mathbf{v}_2$ is in the kernel. If θ is the only vector in the kernel, then $\mathbf{v}_1 - \mathbf{v}_2 = \theta$ and so $\mathbf{v}_1 = \mathbf{v}_2$.

3. For the matrix

$$A = \begin{pmatrix} 2 & -1 & 2 \\ 0 & 3 & -2 \\ 0 & 2 & -2 \end{pmatrix}$$

(a) Compute the eigenvalues and a basis for each eigenspace.

(b) Compute an invertible matrix Q and a diagonal matrix D such that $Q^{-1}AQ = D$. You need not compute Q^{-1} .

(c) Compute the general solution of the differential equation $\frac{dX}{dt} = AX$.

(a)

$$xI - A = \begin{pmatrix} x-2 & 1 & -2 \\ 0 & x-3 & 2 \\ 0 & -2 & x+2 \end{pmatrix}$$

So $\det(xI - A) = (x-2)(x^2 - x - 6 + 4) = (x-2)(x-2)(x+1)$. The eigenvalues are 2, -1.

With $l = 2$

$$2I - A = \begin{pmatrix} 0 & 1 & -2 \\ 0 & -1 & 2 \\ 0 & -2 & 4 \end{pmatrix} \quad \text{which is row equivalent to} \quad \begin{pmatrix} 0 & 1 & -2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

A basis for the null space is

$$\mathbf{e}_r = \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix}, \quad \mathbf{e}_s = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}.$$

With $l = -1$

$$2I - A = \begin{pmatrix} -3 & 1 & -2 \\ 0 & -4 & 2 \\ 0 & -2 & 1 \end{pmatrix} \quad \text{which is row equivalent to} \quad \begin{pmatrix} 1 & 0 & 1/2 \\ 0 & 1 & -1/2 \\ 0 & 0 & 0 \end{pmatrix}$$

with eigenvector $\begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix}$

(b)

$$P = \begin{pmatrix} 0 & 1 & -1 \\ 2 & 0 & 1 \\ 1 & 0 & 2 \end{pmatrix} \quad \text{with the diagonal matrix} \quad \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

(c)

$$X(t) = c_1 e^{2t} \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix} + c_2 e^{2t} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + c_3 e^{-t} \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix}.$$

4. Define the linear map $L : \mathcal{P}_1 \rightarrow \mathcal{P}_2$ (polynomials p of degree at most 1 and at most 2, respectively) by $L(p)(x) = (x^2 + 1)p(1) + p(x)$. With respect to the basis $\mathcal{B} = \{x - 1, 1\}$ for \mathcal{P}_1 and $\mathcal{B}' = \{x^2, x, 1\}$ for \mathcal{P}_2 , compute the matrix $[L]_{\mathcal{B}' \mathcal{B}}$ of the linear map.

$L(x - 1) = x - 1, L(1) = x^2 + 2$. So

$$[L]_{\mathcal{B}' \mathcal{B}} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \\ -1 & 2 \end{pmatrix}.$$

5. The columns of the matrix

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & -1 & 1 \\ 0 & 1 & 1 \\ 0 & -1 & 1 \end{pmatrix}$$

are linearly independent.

Use the Gram-Schmidt procedure to obtain an orthonormal basis for the column space and use it to compute the orthogonal projection of the vector

$\begin{pmatrix} 0 \\ 0 \\ -4 \\ 4 \end{pmatrix}$ onto the column space.

With the columns $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$, the orthogonal list is given by

$$\begin{aligned} \mathbf{w}_1 &= \mathbf{v}_1, \mathbf{w}_2 = \mathbf{v}_2 - \frac{\mathbf{v}_2 \cdot \mathbf{w}_1}{\mathbf{w}_1 \cdot \mathbf{w}_1} \mathbf{w}_1, \\ \mathbf{w}_3 &= \mathbf{v}_3 - \frac{\mathbf{v}_3 \cdot \mathbf{w}_1}{\mathbf{w}_1 \cdot \mathbf{w}_1} \mathbf{w}_1 - \frac{\mathbf{v}_3 \cdot \mathbf{w}_2}{\mathbf{w}_2 \cdot \mathbf{w}_2} \mathbf{w}_2 \end{aligned}$$

$$\mathbf{w}_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \mathbf{w}_2 = \begin{pmatrix} 1 \\ -1 \\ 1 \\ -1 \end{pmatrix} - 0,$$

$$\mathbf{w}_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} - \frac{2}{2} \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix} - 0 = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix}.$$

For the orthonormal basis we divide by the lengths so that

$$\mathbf{u}_1 = \frac{1}{\sqrt{2}}\mathbf{w}_1, \quad \mathbf{u}_2 = \frac{1}{2}\mathbf{w}_2, \quad \mathbf{u}_3 = \frac{1}{\sqrt{2}}\mathbf{w}_3$$

$$P_U(\mathbf{v}) = (\mathbf{v} \cdot \mathbf{u}_1)\mathbf{u}_1 + (\mathbf{v} \cdot \mathbf{u}_2)\mathbf{u}_2 + (\mathbf{v} \cdot \mathbf{u}_3)\mathbf{u}_3$$

With $\mathbf{v} = \begin{pmatrix} 0 \\ 0 \\ -4 \\ 4 \end{pmatrix}$,

$$P_U(\mathbf{v}) = 0 - (-4)\frac{1}{2} \begin{pmatrix} 1 \\ -1 \\ 1 \\ -1 \end{pmatrix} - 0 = \begin{pmatrix} -2 \\ 2 \\ -2 \\ 2 \end{pmatrix}$$

6. (14 points) Let $\{X_1, \dots, X_k\}$ be a list of nonzero vectors in \mathbb{R}^n .

(a) Define what it means for the list to be orthogonal.

(b) Show that if the list is orthogonal, then it is linearly independent.

(a) The dot products $X_i \cdot X_j = (X_i)^T X_j$ all equal 0 when $i \neq j$.

(b) If $c_1 X_1 + \dots + c_k X_k = \theta$ we must show all the c_i 's equal 0. The dot product with X_i is $c_i (X_i)^T X_i = 0$ and since X_i is not the zero vector, $(X_i)^T X_i > 0$ and so $c_i = 0$.

7. For the matrix

$$A = \begin{pmatrix} 3 & 0 & 1 & 0 \\ 0 & 3 & 0 & -1 \\ 1 & 0 & 3 & 0 \\ 0 & -1 & 0 & 3 \end{pmatrix}$$

the eigenvalues are 4 and 2. Compute an orthogonal matrix P and a diagonal matrix D such that $P^{-1}AP = D$. Compute the inverse of P as well (Hint: P is orthogonal).

With $l = 4$

$$4I - A = \begin{pmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & 1 \\ -1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{pmatrix} \text{ is row equivalent to } \begin{pmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

So a basis for the null space is

$$\mathbf{e}_r = \begin{pmatrix} 0 \\ -1 \\ 0 \\ 1 \end{pmatrix}, \quad \mathbf{e}_s = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}.$$

With $l = 2$

$$2I - A = \begin{pmatrix} -1 & 0 & -1 & 0 \\ 0 & -1 & 0 & 1 \\ -1 & 0 & -1 & 0 \\ 0 & 1 & 0 & -1 \end{pmatrix} \text{ is row equivalent to } \begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

So a basis for the null space is

$$\mathbf{e}_r = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix}, \quad \mathbf{e}_s = \begin{pmatrix} -1 \\ 0 \\ 1 \\ 0 \end{pmatrix}.$$

The four vectors form an orthogonal list. To obtain P we need an orthonormal list and so we divide by the lengths which are all $\sqrt{2}$. So

$$P = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 & -1 \\ -1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 \end{pmatrix} \text{ and the diagonal matrix is } \begin{pmatrix} 4 & 0 & 0 & 0 \\ 0 & 4 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 2 \end{pmatrix}$$

Because P is orthogonal,

$$P^{-1} = P^T = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & -1 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ -1 & 0 & 1 & 0 \end{pmatrix}$$