

SHOW ALL WORK. Answer 5 questions from Part I and 2 from Part II

PART I. Answer 5 complete questions from this part. (14 points each)

1. a) Let  $A$  be the matrix 
$$\begin{pmatrix} 0 & 1 & -2 & -2 \\ 0 & 1 & -2 & 1 \\ 1 & 2 & -1 & 0 \\ 3 & 2 & 1 & 1 \end{pmatrix}.$$

Find the determinants of the following matrices: i)  $A$ , ii)  $A^{-1}$  and iii)  $2A^3$

b) Let  $B = \begin{pmatrix} 1 & 2 & -1 \end{pmatrix}$  and  $C = \begin{pmatrix} -2 \\ 3 \\ 1 \end{pmatrix}$ . Find i)  $BC$  and ii)  $B^T C^T$ .

2. Use Gaussian elimination to solve each of the following systems of equations. In part a), write the solution as a linear combination of vectors.

a) 
$$\begin{cases} 3x - y + z = 0 \\ 2x + 4y - 2w = 2 \\ -7y + z + 3w = -3 \end{cases}$$
 b) 
$$\begin{cases} x - y + 3z = 0 \\ 2x - y + 2z = 0 \\ x - z = 1 \end{cases}$$

3. a) Find the inverse of the matrix  $A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 4 & 8 \\ 1 & 2 & 4 \end{pmatrix}.$

b) Use the matrix  $A^{-1}$  that you found in (a) to solve the system 
$$\begin{cases} x + 2y + 3z = 1 \\ 4y + 8z = -1 \\ x + 2y + 4z = 4 \end{cases}$$

4. a) Find the surface area of the part of the sphere  $x^2 + y^2 + z^2 = 4$  that lies above the plane  $z = 1$ .

b) Let  $S$  be the surface parametrized by  $x = u + 3$ ;  $y = v + 2$ ;  $z = uv^2$ . Show that the point  $P$  with  $(x, y, z)$  co-ordinates  $(4, 4, 4)$  lies on  $S$  and find an equation of the tangent plane to  $S$  at point  $P$ .

5. a) Find the eigenvalues and eigenvectors of the matrix  $A = \begin{pmatrix} 6 & 1 \\ -3 & 2 \end{pmatrix}.$

b) Use your answer to part a) to solve the following simultaneous differential equations for  $y_1(t)$  and  $y_2(t)$  subject to initial conditions  $y_1(0) = 1$  and  $y_2(0) = 2$ :

$$\begin{cases} y_1' = 6y_1 + y_2 \\ y_2' = -3y_1 + 2y_2 \end{cases}$$

Please turn the page for the continuation of Part I and for Part II

**Part I, continued**

6. Let  $\vec{F}(x, y, z) = \left\langle \frac{\ln y}{2\sqrt{x}} + yz, \frac{\sqrt{x}}{y} + xz, xy \right\rangle$ .

a) Find a potential function  $f(x, y, z)$  for  $\vec{F}$  so that  $\nabla f = \vec{F}$  and

b) Evaluate  $\int_C \vec{F} \cdot d\vec{r}$  where  $C$  is the straight line segment from  $P(1, e, 1)$  to  $Q(4, e^2, 2)$ .

7. a) Let  $S$  be the surface described by  $x^2 + y^2 = 1; 0 \leq z \leq 3$ . Evaluate the

integral  $\iint_S z^2 dS$ .

b) Find the length of the part of the parametrized curve  $\vec{r}(t) = \left\langle \frac{t^2}{2}, \frac{2\sqrt{2}}{3}t^{3/2}, t \right\rangle$

between the points  $P(0, 0, 0)$  and  $Q\left(\frac{1}{2}, \frac{2\sqrt{2}}{3}, 1\right)$ .

**End of Part I. Make sure you answered five complete questions from this part.**

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**PART II: Answer 2 complete questions from this part (15 points each).**

8. Let  $R$  be the region in the  $x, y$ -plane bounded by the curves  $x = y^2$  and  $y = x - 2$ .

Find  $\int_C -y dx + x dy$  (where  $C$  is the boundary of  $R$ , oriented clockwise)

a) directly, as a line integral **AND**

b) as a double integral, by using Green's Theorem.

9. Let  $S$  be the surface described by  $z = x^2 + y^2; z \leq 4; y \geq 0$  and let  $C$  be the boundary curve of  $S$  with the orientation of your choice. Let  $\vec{F}(x, y, z) = \langle y, z, x \rangle$ . Find  $\int_C \vec{F} \cdot d\vec{r}$

a) directly as a line integral **AND** b) as a double integral, by using Stokes' Theorem.

10. Let  $T$  be the solid bounded below by  $z = 0$ , bounded above by  $y + z = 1$ , and bounded on the side by  $x^2 + y^2 = 1$ . Let  $S$  be the boundary surface of  $T$ . Let

$\vec{F}(x, y, z) = \langle x, y, z \rangle$ . Use the outward pointing normal vector to evaluate  $\iint_S \vec{F} \cdot d\vec{S}$

a) directly as a surface integral **AND**

b) as a triple integral, by using the Divergence Theorem.

**END OF EXAM. Please check that you answered five complete questions from Part I and two complete questions from Part II.**

# Math 39200, Spring 2006 Final Exam Solutions

## Part I

①

(a)

$$A = \begin{bmatrix} 0 & 1 & -2 & -2 \\ 0 & 1 & -2 & 1 \\ 1 & 2 & -1 & 0 \\ 3 & 2 & 1 & 1 \end{bmatrix}$$

$-3R_3 + R_4 \rightarrow R_4$

$$\begin{bmatrix} 0 & 1 & -2 & -2 \\ 0 & 1 & -2 & 1 \\ 1 & 2 & -1 & 0 \\ 0 & -4 & 4 & 1 \end{bmatrix} \quad (1) R_1 + R_2 \rightarrow R_2$$

expanding along first column

$$\Rightarrow \det(A) = 1(-1)^{3+1} \begin{vmatrix} 1 & -2 & -2 \\ 1 & -2 & 1 \\ -4 & 4 & 1 \end{vmatrix} = \begin{vmatrix} 1 & -2 & -2 \\ 0 & 0 & 3 \\ -4 & 4 & 1 \end{vmatrix}$$

expanding along second row

$$= 3(-1)^{2+3} \begin{vmatrix} 1 & -2 \\ -4 & 4 \end{vmatrix} = -3(-4) = 12$$

i) 12

ii)  $\det(A^{-1}) = \frac{1}{\det(A)} = \frac{1}{\span style="border: 1px solid black; padding: 2px;">12}}$

iii)  $\det(2A^3) = (2)^4 (\det(A))^3 = \span style="border: 1px solid black; padding: 2px;">16(12)^3$

(b) i)  $BC = (1 \ 2 \ -1) \begin{pmatrix} -2 \\ 3 \\ 1 \end{pmatrix} = -2 + 6 - 1 = \span style="border: 1px solid black; padding: 2px;">3$

ii)  $B^T C^T = \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} \begin{pmatrix} -2 & 3 & 1 \end{pmatrix} = \begin{pmatrix} -2 & 3 & 1 \\ -4 & 6 & 2 \\ 2 & -3 & -1 \end{pmatrix} \leftarrow 3 \times 3$

$3 \times 1 \quad 1 \times 3$

$$\textcircled{2} \text{ (a)} \begin{array}{cccc|c} x & y & z & w & \\ \hline 3 & -1 & 1 & 0 & 0 \\ 2 & 4 & 0 & -2 & 2 \\ 0 & -7 & 1 & 3 & -3 \end{array} \xrightarrow{R_1 \leftrightarrow R_2}$$

$$\begin{array}{cccc|c} 2 & 4 & 0 & -2 & 2 \\ 3 & -1 & 1 & 0 & 0 \\ 0 & -7 & 1 & 3 & -3 \end{array} \xrightarrow{\frac{1}{2}R_1 \rightarrow R_1} \begin{array}{cccc|c} 1 & 2 & 0 & -1 & 1 \\ 3 & -1 & 1 & 0 & 0 \\ 0 & -7 & 1 & 3 & -3 \end{array}$$

$$\xrightarrow{-3R_1 + R_2 \rightarrow R_2} \begin{array}{cccc|c} 1 & 2 & 0 & -1 & 1 \\ 0 & -7 & 1 & 3 & -3 \\ 0 & -7 & 1 & 3 & -3 \end{array} \xrightarrow{-R_2 + R_3 \rightarrow R_3} \begin{array}{cccc|c} 1 & 2 & 0 & -1 & 1 \\ 0 & -7 & 1 & 3 & -3 \\ 0 & 0 & 0 & 0 & 0 \end{array}$$

(NOTE: Technically did not complete Gaussian elimination as matrix is not in r.r.e.f.)

$$\begin{aligned} \Rightarrow x + 2y - w &= 1 \\ -7y + z + 3w &= -3 \end{aligned} \Rightarrow \begin{aligned} x &= -2y + w + 1 \\ z &= 7y - 3w - 3 \end{aligned} \quad \left( \begin{array}{l} \text{I am treating } y \text{ \& } w \\ \text{as free variables, } x \text{ \& } z \\ \text{as leading.} \end{array} \right)$$

general solution

$$\begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} = \begin{pmatrix} -2y + w + 1 \\ y \\ 7y - 3w - 3 \\ w \end{pmatrix} = y \begin{pmatrix} -2 \\ 1 \\ 7 \\ 0 \end{pmatrix} + w \begin{pmatrix} 1 \\ 0 \\ -3 \\ 1 \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \\ -3 \\ 0 \end{pmatrix}, y, w \in \mathbb{R}$$

$$\textcircled{b} \begin{array}{ccc|c} x & y & z & \\ \hline 1 & -1 & 3 & 0 \\ 2 & -1 & 2 & 0 \\ 1 & 0 & -1 & 1 \end{array} \xrightarrow{\begin{array}{l} -2R_1 + R_2 \rightarrow R_2 \\ -R_1 + R_3 \rightarrow R_3 \end{array}} \begin{array}{ccc|c} 1 & -1 & 3 & 0 \\ 0 & 1 & -4 & 0 \\ 0 & 1 & -4 & 1 \end{array}$$

⇒ This system is inconsistent. We cannot have

$$y - 4z = 0 \quad \text{AND} \quad y - 4z = 1 \quad \text{because } 0 \neq 1!$$

⇒ The system has no solution.

$$\textcircled{3} \text{ (a)} \left[ \begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 4 & 8 & 0 & 1 & 0 \\ 1 & 2 & 4 & 0 & 0 & 1 \end{array} \right]$$

$$\begin{array}{l} -R_1 + R_3 \rightarrow R_3 \\ \frac{1}{4} R_2 \rightarrow R_2 \end{array} \left[ \begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & 2 & 0 & \frac{1}{4} & 0 \\ 0 & 0 & 1 & -1 & 0 & 1 \end{array} \right] \begin{array}{l} -3R_3 + R_1 \rightarrow R_1 \\ -2R_3 + R_2 \rightarrow R_2 \end{array}$$

$$\left[ \begin{array}{ccc|ccc} 1 & 2 & 0 & 4 & 0 & -3 \\ 0 & 1 & 0 & 2 & \frac{1}{4} & -2 \\ 0 & 0 & 1 & -1 & 0 & 1 \end{array} \right] \xrightarrow{-2R_2 + R_1 \rightarrow R_1} \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & 0 & -\frac{1}{2} & 1 \\ 0 & 1 & 0 & 2 & \frac{1}{4} & -2 \\ 0 & 0 & 1 & -1 & 0 & 1 \end{array} \right] \underbrace{\hspace{10em}}_{A^{-1}}$$

(b) The coefficient matrix of the system is the matrix  $A$  from part (a).

So the (unique) solution to the system is

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = A^{-1} \begin{pmatrix} 1 \\ -1 \\ 4 \end{pmatrix} = \begin{pmatrix} 0 & -\frac{1}{2} & 1 \\ 2 & \frac{1}{4} & -2 \\ -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ -1 \\ 4 \end{pmatrix} = \begin{pmatrix} 4\frac{1}{2} \\ -6\frac{1}{4} \\ 3 \end{pmatrix}$$

④ (a)  $z = \sqrt{4-x^2-y^2}$ , since  $z \geq 1 \Rightarrow z \geq 0$

$$r(x,y) = \langle x, y, \sqrt{4-x^2-y^2} \rangle \quad (x^2+y^2 \leq 3)$$

$$r_x = \langle 1, 0, \frac{-x}{\sqrt{4-x^2-y^2}} \rangle$$

$$r_y = \langle 0, 1, \frac{-y}{\sqrt{4-x^2-y^2}} \rangle$$

$$\Rightarrow r_x \times r_y = \left\langle \frac{x}{\sqrt{4-x^2-y^2}}, \frac{y}{\sqrt{4-x^2-y^2}}, 1 \right\rangle$$

$$\Rightarrow \|r_x \times r_y\| = \sqrt{\frac{x^2+y^2+4-x^2-y^2}{4-x^2-y^2}} = \frac{2}{\sqrt{4-x^2-y^2}}$$

$$\Rightarrow A(S) = \iint_S dS = \iint \frac{2}{\sqrt{4-x^2-y^2}} dA = \int_0^{2\pi} \int_0^{\sqrt{3}} \frac{2}{\sqrt{4-r^2}} r dr d\theta$$

$$= \int_0^{2\pi} \left[ -2 \cdot u^{1/2} \right]_1^2 d\theta = 2\pi \cdot 2 \cdot u^{1/2} \Big|_1^2 = \boxed{4\pi(\sqrt{2}-1)}$$

(b)  $r(u,v) = \langle u+3, v+2, uv^2 \rangle$

$$r_u = \langle 1, 0, v^2 \rangle$$

$$\Rightarrow r_u \times r_v = \langle -v^2, -2uv, 1 \rangle = n$$

$$r_v = \langle 0, 1, 2uv \rangle$$

$(4, 4, 4)$  lies on  $S$  because  $r\left(\overset{u}{1}, \overset{v}{2}\right) = \langle 4, 4, 4 \rangle$  &  $n = \langle -4, -4, 1 \rangle$  at this point

So an equation for the tangent plane to  $S$  at  $(4, 4, 4)$  is:

$$\boxed{-4(x-4) + (-4)(y-4) + 1 \cdot (z-4) = 0}$$

⑤ (a)  $\det(A-\lambda I) = \begin{vmatrix} 6-\lambda & 1 \\ -3 & 2-\lambda \end{vmatrix} = (6-\lambda)(2-\lambda) + 3 = \lambda^2 - 8\lambda + 15 = (\lambda-3)(\lambda-5)$

$\Rightarrow$  eigenvalues of  $A$ : 3 and 5

$$\underline{\lambda = 3}$$

$$A - \lambda I = \begin{bmatrix} 3 & 1 \\ -3 & -1 \end{bmatrix} \xrightarrow[\downarrow]{\text{row reduces to}} \begin{bmatrix} 3 & 1 \\ 0 & 0 \end{bmatrix} \rightarrow \begin{cases} 3x_1 + x_2 = 0 \\ \Rightarrow x_2 = -3x_1 \end{cases}$$

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} x_1 \\ -3x_1 \end{pmatrix} \Rightarrow \text{eigenvectors: } \begin{pmatrix} r \\ -3r \end{pmatrix}, r \in \mathbb{R}$$

$$\underline{\lambda = 5}$$

$$A - \lambda I = \begin{bmatrix} 1 & 1 \\ -3 & -3 \end{bmatrix} \xrightarrow[\downarrow]{\text{row reduces to}} \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \rightarrow \begin{cases} x_1 + x_2 = 0 \\ \Rightarrow x_1 = -x_2 \end{cases}$$

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} -x_2 \\ x_2 \end{pmatrix} \Rightarrow \text{eigenvectors: } \begin{pmatrix} -s \\ s \end{pmatrix}, s \in \mathbb{R}$$

(b) coefficient matrix of the system is the matrix A from part (a)

$$\Rightarrow \underline{\text{general solution:}} \quad y = y_I + y_{II} = \begin{pmatrix} r e^{3t} \\ -3r e^{3t} \end{pmatrix} + \begin{pmatrix} -s e^{5t} \\ s e^{5t} \end{pmatrix}$$

$$\Rightarrow \begin{cases} y_1(t) = r e^{3t} - s e^{5t} \\ y_2(t) = -3r e^{3t} + s e^{5t} \end{cases} \Rightarrow \text{particular solution: } \begin{cases} y_1(0) = r - s = 1 \\ y_2(0) = -3r + s = 2 \end{cases} \Rightarrow \begin{cases} -2r = 3 \\ r = -\frac{3}{2} \end{cases}$$

$$\hookrightarrow \begin{cases} y_1(t) = -\frac{3}{2} e^{3t} + \frac{5}{2} e^{5t} \\ y_2(t) = \frac{9}{2} e^{3t} - \frac{5}{2} e^{5t} \end{cases}$$

$$\Rightarrow \begin{cases} s = -\frac{5}{2} \\ s = \frac{5}{2} \end{cases}$$

⑥ (a)  $\frac{df}{dx} = \frac{\ln y}{2\sqrt{x}} + yz \Rightarrow f(x, y, z) = \sqrt{x} \ln y + xyz + g(y, z)$

\*  $\frac{df}{dy} = \frac{\sqrt{x}}{y} + xz \Rightarrow \frac{df}{dy} = \frac{\sqrt{x}}{y} + xz + \frac{dg}{dy}$

$\Rightarrow \frac{dg}{dy} = 0$  by comparison to \*

\*\*  $\frac{df}{dz} = xy \Rightarrow g(y, z) = h(z)$  (because  $g$  is constant with respect to  $y$ )

$\Rightarrow f(x, y, z) = \sqrt{x} \ln y + xyz + h(z)$

$\Rightarrow \frac{df}{dz} = xy + h'(z)$

$\Rightarrow h'(z) = 0$  by comparison to \*\*

$\Rightarrow \boxed{f(x, y, z) = \sqrt{x} \ln y + xyz + k}$  ← constant

↑  
general potential function

(b) Since part (a) demonstrates that  $F$  is conservative (on the portion of  $\mathbb{R}^3$  where  $y > 0$  and  $x > 0$ ) we can evaluate

$\int_C F \cdot dr$  by letting  $k=0$  in our general potential function and calculating  $f(4, e^2, 2) - f(1, e, 1) =$

$$[\sqrt{4} \ln(e^2) + 4(e^2)(2)] - [\sqrt{1} \ln(e) + 1(e)(1)]$$

$$= \boxed{3 + 8e^2 - e}$$

(You may evaluate this directly if you like.)

⑦ (a)  $r(\theta, z) = \langle \cos \theta, \sin \theta, z \rangle, 0 \leq \theta \leq 2\pi, 0 \leq z \leq 3$

$r_\theta = \langle -\sin \theta, \cos \theta, 0 \rangle \Rightarrow r_\theta \times r_z = \langle \cos \theta, \sin \theta, 0 \rangle$

$r_z = \langle 0, 0, 1 \rangle$

$\Rightarrow \|r_\theta \times r_z\| = 1$



$$\Rightarrow \iint_S z^2 dS = \iint z^2(1) dA = \int_0^3 \int_0^{2\pi} z^2 d\theta dz = 2\pi \cdot \left[ \frac{z^3}{3} \right]_0^3 = \boxed{18\pi}$$

(b) At P,  $t=0$ . At Q,  $t=1$ .

So the length of the curve given by  $r(t)$  from P to Q is given by  $\int_0^1 \|r'(t)\| dt$

$$r(t) = \left\langle \frac{t^2}{2}, \frac{2\sqrt{2}}{3} t^{3/2}, t \right\rangle \Rightarrow r'(t) = \langle t, \sqrt{2} t^{1/2}, 1 \rangle$$

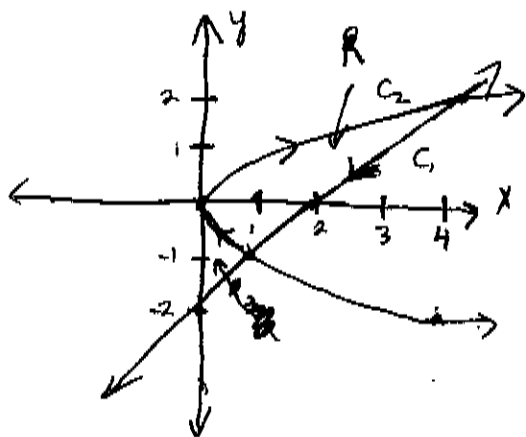
$$\Rightarrow \|r'(t)\| = \sqrt{t^2 + 2t + 1} = \sqrt{(t+1)^2}$$

$$= t+1 \quad \text{BECAUSE } t \geq 0 \text{ so certainly } t \geq -1$$

$$\Rightarrow \int_0^1 \|r'(t)\| dt = \int_0^1 (t+1) dt = \left[ \frac{t^2}{2} + t \right]_0^1 = \boxed{\frac{3}{2}}$$

## Part II

8



$$F = \langle -y, x \rangle$$

$\uparrow$       $\uparrow$   
 P     Q

(a)  $C_1: r(x) = \langle x, x-2 \rangle, 1 \leq x \leq 4$  (goes 'wrong' way)

$$\int_{C_1} F \cdot dr = - \int_1^4 (2-x) dx = \int_1^4 x dx = \int_1^4 -2 dx = -2x \Big|_1^4 = \boxed{-6}$$

$C_2: r(y) = \langle y^2, y \rangle, -1 \leq y \leq 2$  (goes 'right' way)

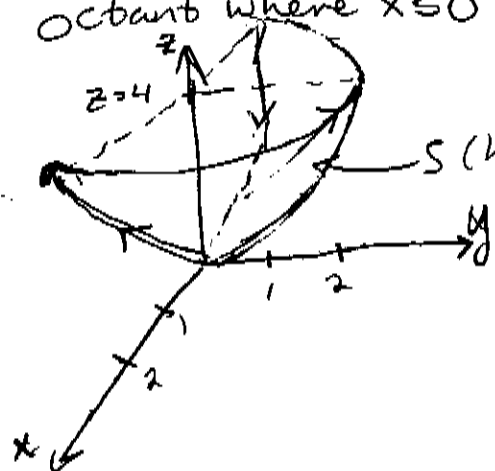
$$\int_{C_2} F \cdot dr = \int_{-1}^2 (-y)(2y dy) + \int_{-1}^2 y^2 dy = \int_{-1}^2 -y^2 dy = -\frac{1}{3} y^3 \Big|_{-1}^2 = \boxed{-3}$$

$$\Rightarrow \int_C F \cdot dr = (-6) + (-3) = \boxed{-9}$$

(b)  $\frac{\partial Q}{\partial x} = 1, \frac{\partial P}{\partial y} = -1 \Rightarrow \int_C F \cdot dr = - \iint_R 2 dA = -2 \int_{-1}^2 \int_{y^2}^{y+2} dx dy$

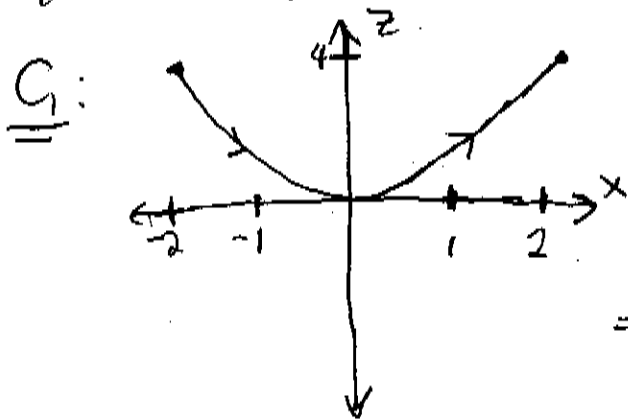
$$= -2 \int_{-1}^2 (y+2-y^2) dy = 2 \left[ \frac{1}{3} y^3 - \frac{y^2}{2} - 2y \right]_{-1}^2 = 2 \left( -\frac{10}{3} - \frac{7}{6} \right) = \boxed{-9}$$

- ⑨ Let's orient  $C$  in such a way that the portion visible looking down at the  $xy$ -plane "moves" from the octant where  $x \geq 0$  to the octant where  $x \leq 0$  (counter-clockwise motion)



$$F = \langle y, z, x \rangle$$

- (a) The boundary of  $S$  can be broken down into two smooth pieces, one which lies in the  $xz$ -plane and the other which lies in the plane  $z=4$ . We will call these two pieces  $C_1$  and  $C_2$  respectively.



$$r(x) = \langle x, 0, x^2 \rangle, -2 \leq x \leq 2$$

~~$$F(r(x)) = \langle 0, x^2, x \rangle$$~~

$$\Delta r'(x) = \langle 1, 0, 2x \rangle$$

$$\Rightarrow F(r(x)) \cdot r'(x) = 2x^2$$

$$\int_{C_1} F \cdot dr = \int_{-2}^2 F(r(x)) \cdot r'(x) dx = \int_{-2}^2 2x^2 dx = \left. \frac{2}{3} x^3 \right|_{-2}^2 = \frac{32}{3}$$

$C_2$ :  $r(\theta) = \langle 2 \cos \theta, 2 \sin \theta, 4 \rangle, 0 \leq \theta \leq \pi$

$$\Rightarrow F(r(\theta)) = \langle 2 \sin \theta, 4, 2 \cos \theta \rangle \quad \& \quad r'(\theta) = \langle -2 \sin \theta, 2 \cos \theta, 0 \rangle$$

$$\Rightarrow F(r(\theta)) \cdot r'(\theta) = -4 \sin^2 \theta + 8 \cos \theta$$

$$\Rightarrow \int_{C_2} F \cdot dr = \int_0^\pi (-4 \sin^2 \theta + 8 \cos \theta) d\theta = -4 \int_0^\pi \frac{1 - \cos(2\theta)}{2} d\theta = \overline{-2\pi}$$

$$\Rightarrow \int_C F \cdot dr = \boxed{\frac{32}{3} - 2\pi}$$

$$(6) \int_C \mathbf{F} \cdot d\mathbf{r} = \iint_S \text{curl} \mathbf{F} \cdot d\mathbf{S}$$

↑  
Stokes'

Parametrization of  $S$ :

$$\mathbf{r}(x,y) = \langle x, y, x^2 + y^2 \rangle \quad (x^2 + y^2 \leq 4)$$

$$\mathbf{r}_x = \langle 1, 0, 2x \rangle$$

$$\mathbf{r}_y = \langle 0, 1, 2y \rangle$$

$$\Rightarrow \mathbf{r}_x \times \mathbf{r}_y = \langle -2x, -2y, 1 \rangle = \mathbf{n}$$

(Use the "right-hand rule" to see that this choice of normal is consistent with the orientation of the boundary of  $S$ )

$$\text{curl} \mathbf{F} = \nabla \times \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y & z & x \end{vmatrix} = \langle -1, -1, -1 \rangle$$

$$\Rightarrow \text{curl} \mathbf{F}(\mathbf{r}(x,y)) = \langle -1, -1, -1 \rangle$$

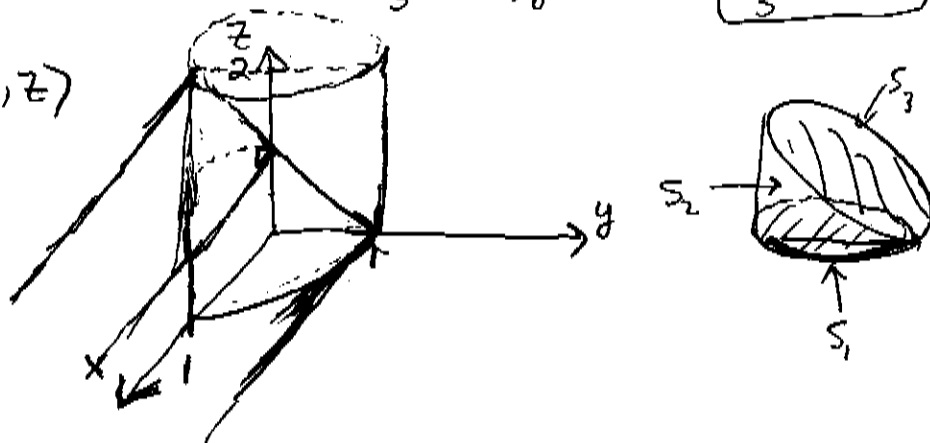
$$\Rightarrow \text{curl} \mathbf{F}(\mathbf{r}(x,y)) \cdot \mathbf{n} = 2x + 2y - 1$$

$$\Rightarrow \iint_S \text{curl} \mathbf{F} \cdot d\mathbf{S} = \iint_S (2x + 2y - 1) dA = \int_0^{2\pi} \int_0^2 (2r \cos \theta + 2r \sin \theta - 1) r dr d\theta$$

$$= \int_0^{2\pi} \left( 2 \sin \theta \left[ \frac{r^3}{3} \right]_0^2 - \left[ \frac{r^2}{2} \right]_0^2 \right) d\theta$$

$$= -\frac{16}{3} (\cos \theta)_0^{2\pi} - 2\pi = \boxed{\frac{32}{3} - 2\pi}$$

(10)  $\mathbf{F} = \langle x, y, z \rangle$



$\leftarrow S$  looks like this

(a) We have to evaluate  $\iint_S F \cdot dS$  in three pieces.

$$\iint_{S_1} F \cdot dS_1$$

Parametrization of  $S_1$ :

$$r(r, \theta) = \langle r \cos \theta, r \sin \theta, 0 \rangle, \quad 0 \leq r \leq 1, \quad 0 \leq \theta \leq 2\pi$$

$$r_r = \langle \cos \theta, \sin \theta, 0 \rangle$$

$$r_\theta = \langle -r \sin \theta, r \cos \theta, 0 \rangle$$

$$\Rightarrow r_r \times r_\theta = \langle 0, 0, r \rangle$$

$\Rightarrow r_\theta \times r_r = \langle 0, 0, -r \rangle$  is an outward-pointing normal

$$F = F(r(r, \theta)) = \langle r \cos \theta, r \sin \theta, 0 \rangle \Rightarrow F \cdot n = 0 \Rightarrow \iint_{S_1} F \cdot dS_1 = 0$$

$$\iint_{S_2} F \cdot dS_2$$

Parametrization of  $S_2$ :

$$r(\theta, z) = \langle \cos \theta, \sin \theta, z \rangle, \quad 0 \leq \theta \leq 2\pi, \quad 0 \leq z \leq 1 - \cos \theta$$

$$\Rightarrow r_\theta = \langle -\sin \theta, \cos \theta, 0 \rangle$$

$$\Rightarrow r_\theta \times r_z = \langle \cos \theta, \sin \theta, 0 \rangle$$

$$\& r_z = \langle 0, 0, 1 \rangle$$

(Verify that this points outward.)

$$F = F(r(\theta, z)) = \langle \cos \theta, \sin \theta, z \rangle \Rightarrow F \cdot n = \cos^2 \theta + \sin^2 \theta = 1$$

$$\Rightarrow \iint_{S_2} F \cdot dS_2 = \iint_{S_2} 1 dA = \int_0^{2\pi} \int_0^{1-\cos \theta} dz d\theta = \int_0^{2\pi} (1 - \cos \theta) d\theta = 2\pi$$

$$\iint_{S_3} F \cdot dS_3$$

Parametrization of  $S_3$ :

$$r(x, y) = \langle x, y, 1-y \rangle \quad (\text{without limits})$$

$$r_x = \langle 1, 0, 0 \rangle$$

$$r_y = \langle 0, 1, -1 \rangle$$

$$\Rightarrow r_x \times r_y = \langle 0, 1, 1 \rangle$$

← points upward;  
could have obtained this  
from equation for plane  
 $y+z=1$

$$F = F(r(x,y)) = \langle x, y, 1-y \rangle$$

$$\Rightarrow F \cdot n = 0 + y + 1 - y = 1$$

$$\Rightarrow \iint_{S_3} F \cdot dS_3 = \iint 1 dA = \int_0^{2\pi} \int_0^1 r dr d\theta = \pi$$

$$\iint_S F \cdot dS = 0 + 2\pi + \pi = \boxed{3\pi}$$

$$(b) \operatorname{div} F = 1 + 1 + 1 = 3$$

$$\iint_S F \cdot dS = \iiint_V \overset{\operatorname{div} F}{3} dV = 3 \int_0^{2\pi} \int_0^1 \int_0^{1-\cos\theta} r dz dr d\theta$$

↑  
Divergence  
Theorem

$$= \frac{3}{2} \int_0^{2\pi} (1 - \cos\theta) d\theta = \frac{3}{2} (2\pi) = \boxed{3\pi}$$