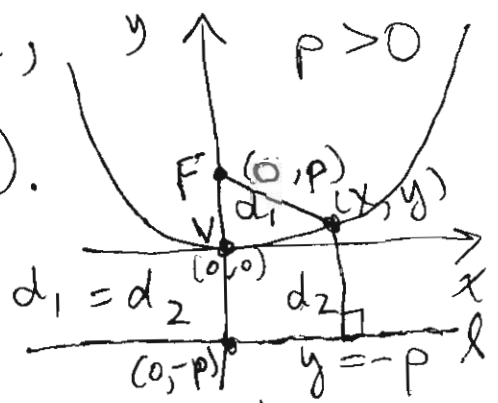


Conics

①

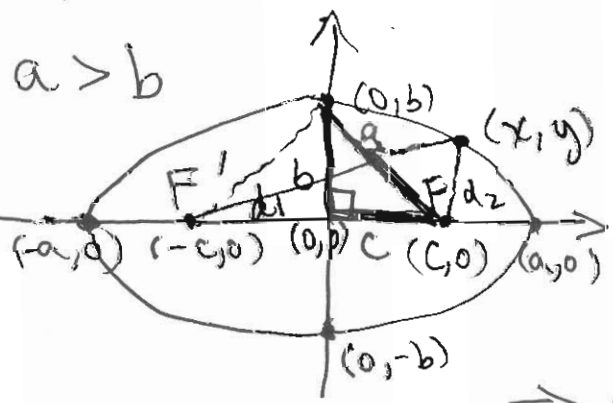
Parabola is a curve whose points are equidistant from a fixed point called the Focus F and a fixed line (that does not contain F) called the directrix l , a distance $2p$ apart.

The vertex V of the parabola is halfway between F & l ($d_1 = d_2 = p$).



In the standard orientation to the right, $x^2 = 4py$; $x^2 = -4py$ is the reflection in the x -axis, while $y^2 = \pm 4px$ are the reflections in the line $y=x$ and open to the right and left, respectively.

Ellipse is a curve whose points have the property that their distances from two fixed points F', F called the foci (plural of focus) sums to a constant $= 2a$ when



$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ in standard form.

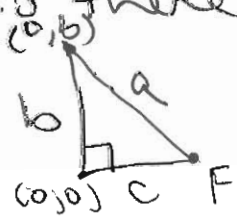
$y = 0 \rightarrow x = \pm a$

$x = 0 \rightarrow y = \pm b$

$d_1 + d_2 = \text{const. applied to } (0, b) = 2a$

$\Rightarrow d_1 = d_2 = a$ due to symmetry

\therefore there is a right triangle (see sketch)



$a^2 = b^2 + c^2$. The intercepts are called the vertices, the line between langer

the vertices also carries the foci and is called the major axis, the line segment joining the other pair of vertices is the minor axis.
 If $b > a$ in the standard equation, the roles of x & y are interchanged and the major axis then lies along the y -axis. Either way, the center of the ellipse is the origin $(0, 0)$ and
 $(\frac{1}{2} \text{ length of major axis})^2 = (\frac{1}{2} \text{ length minor axis})^2 + (\text{dist. bet. } (0, 0) \text{ \& } F)^2$.

Hyperbola is a curve whose points have the property that the difference of their distances from two fixed points F', F (also called the foci) is a constant $= 2a$ when

$$\frac{x^2}{a^2} - \frac{y^2}{b^2} = 1 \text{ in standard form.}$$

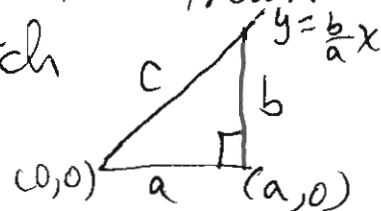
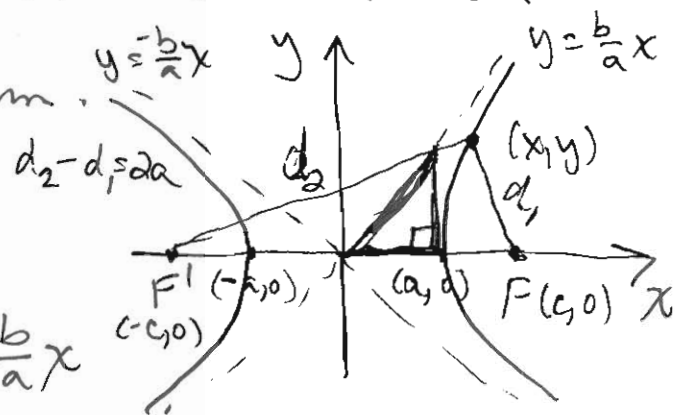
$x=0$ has no solution in y

$$y=0 \Rightarrow x = \pm a$$

$$\lim_{x \rightarrow \pm\infty} y = \lim_{x \rightarrow \pm\infty} \pm \sqrt{b^2 \left(\frac{x^2}{a^2} - 1 \right)} = \pm \frac{b}{a} x$$

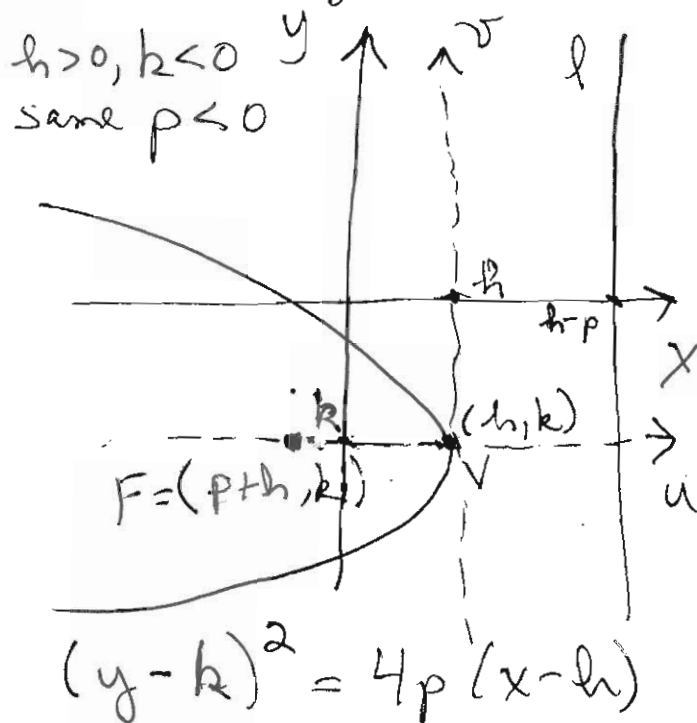
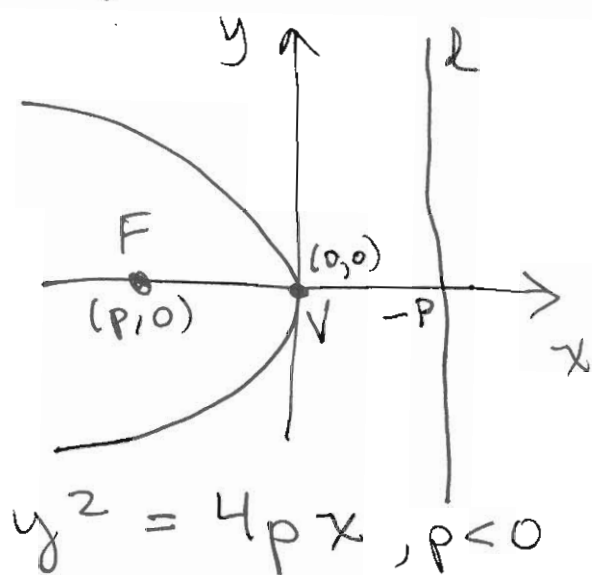
so the lines $y = \pm \frac{b}{a} x$ are oblique (or slant) asymptotes

(see Stewart 3.4 # 39-42). Since slope = rise/run the right triangle formed in the sketch has the property $c^2 = a^2 + b^2$:

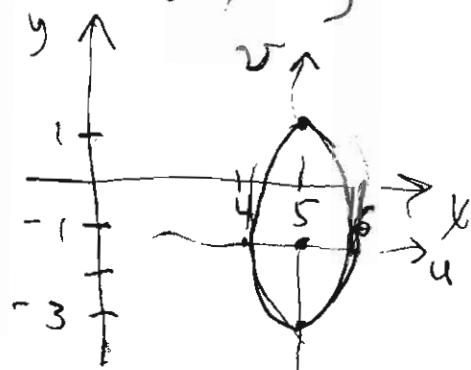


Translation is done just as in calc. I: ③

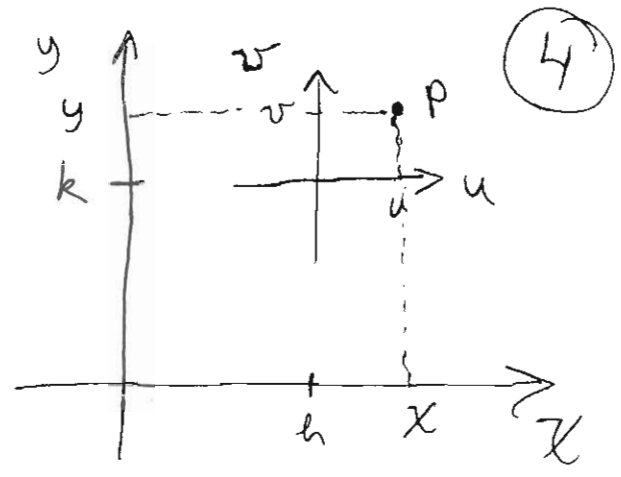
if $f(x, y) = \text{const.}$ represents a curve, then $f(x-h, y-k) = \text{same const.}$ represents the same geometric curve translated to a new rectangular coordinate system whose origin is (h, k) and whose axes are $x-h$ and $y-k$, i.e. letting $u = x-h$ and $v = y-k$ one obtains $f(x, y) = f(u, v)$, $f(0, 0) = f(h, k)$ and the curve relative to the uv -coordinate system looks like the original curve relative to the xy -coordinates.



So, for example, an ellipse whose vertices are $(5, -3)$, $(5, 1)$, $(4, -1)$ and $(6, -1)$ is a vertical ellipse whose center is $(5, -1)$ with

$$\frac{u^2}{1} + \frac{v^2}{2^2} = 1 = \frac{(x-5)^2}{1} + \frac{(y+1)^2}{2^2}$$


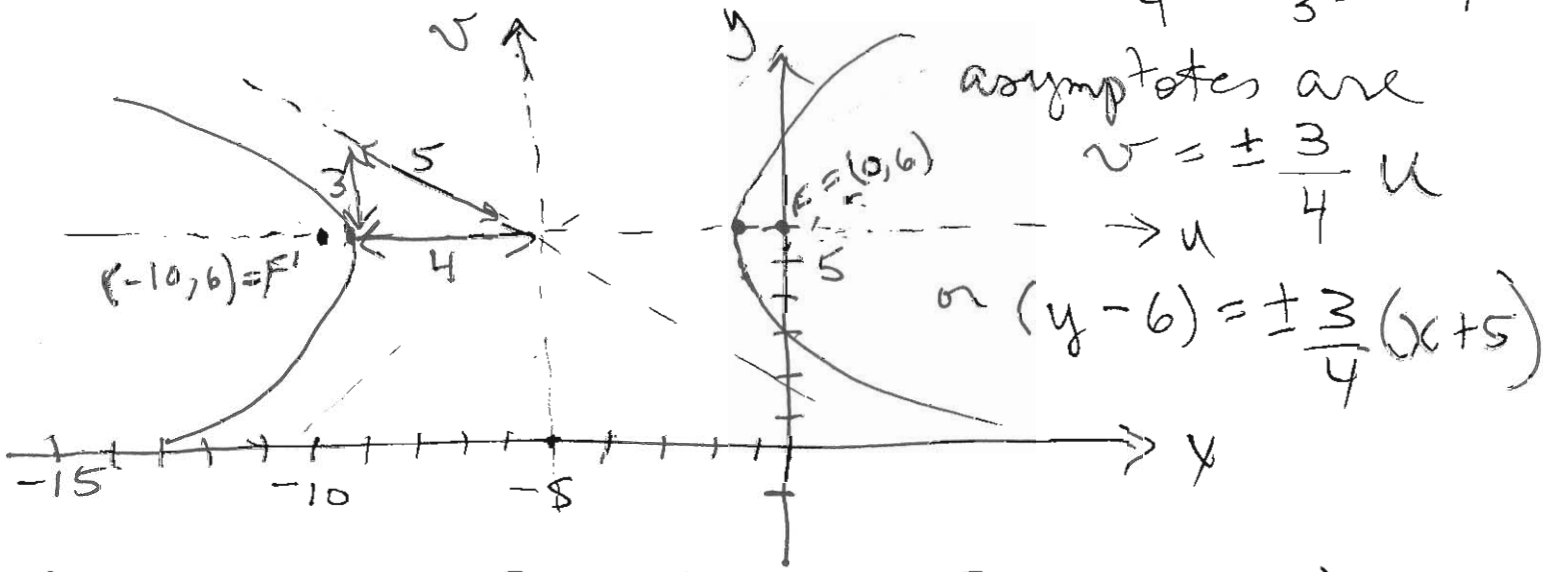
because a point P whose coordinates are (u, v) in the translated system has $(k+v)$ as its y -coordinate and $(h+u)$ as its x -coordinate:



Alternatively, given $9x^2 - 16y^2 + 90x + 192y = 495$ completing the squares in x and y gives

$$\frac{(x+5)^2}{16} - \frac{(y-6)^2}{9} = 1 \quad \text{which is a horizontal hyperbola with center } (-5, 6) = (h, k),$$

$(-5 \pm \sqrt{16}, 6)$ as vertices, i.e. $(-9, 6)$ and $(-1, 6)$, and foci $(-5 \pm \sqrt{25}, 6)$, since $\frac{u^2}{4^2} - \frac{v^2}{3^2} = 1$



In general, $Ax^2 + Cy^2 + Dx + Ey + F = 0$ is a translated conic, a degenerate conic (point, line, pair of lines, eg. when $x^2 + y^2 = 0$, $x = \text{const}$, $y^2 = \text{const}$ giving \parallel lines or $x^2 - y^2 = 0$ giving an intersecting pair), or has no solution (eg. $x^2 + y^2 = \text{const} < 0$).

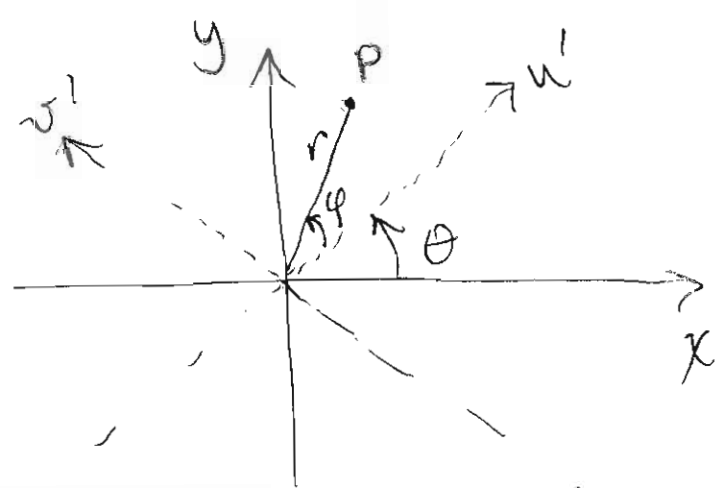
Rotation occurs when the cross-term in the most general quadratic in x and y is

non-zero: $Ax^2 + Bxy + Cy^2 + Dx + Ey + F = 0.$

To eliminate the cross-term, the Cartesian coordinate system (i.e. the xy or uv -coordinate system, depending on whether translation is also a factor) must be rotated by $0 \leq \theta \leq \frac{\pi}{2}$ in the counterclockwise direction, where

$\cot 2\theta = \frac{A-C}{B}$: for example, in the

absence of translation if the point P is a distance r from the mutual origin of the xy and $u'v'$ -coordinate systems, and the



radial line from $(0,0)$ to P makes an angle ϕ with respect to the u' -axis, then it makes an angle of $(\phi + \theta)$ with respect to the x -axis, etc., and $P = (r \cos \phi, r \sin \phi)$ in the $u'v'$ -coordinate system, but in the xy -system P has coordinates $(r \cos(\theta + \phi), r \sin(\theta + \phi)) = (\underbrace{u' \cos \theta - v' \sin \theta}_x, \underbrace{u' \sin \theta + v' \cos \theta}_y).$